

Zephyr Drone Simulator



_{FM} GPS см IOCOff н North 🛛 0016.94 FT 👫 ₀ 👁 ₀ s 0000.04 MPH 🗚 0008.34 FT 卤 97% 🗧



Joseph M. Burgett, PhD Associate Professor



Introduction

· Joe Burgett, PhD

- Clemson Professor
- General Contractor
- Part 107 pilot
- Training for SCDOT
- Research: Applied Drone
 Technology







Value of a Simulator

- Convenient
- Low cost
 - Equipment, time, and effort
- Consistent environmental conditions
 - Testing and monitoring improvement
- Free!
 - FHWA STIC incentive funds
 - Zephyr Drone Simulator







Web-based Download





Client

Engine

CONNECTI... ContextCa... ContextCa... ContextCa... Master Editor CO...

Viewer



Little Arms Launcher

FLIR Thermal FLIR for class DJI Thermal

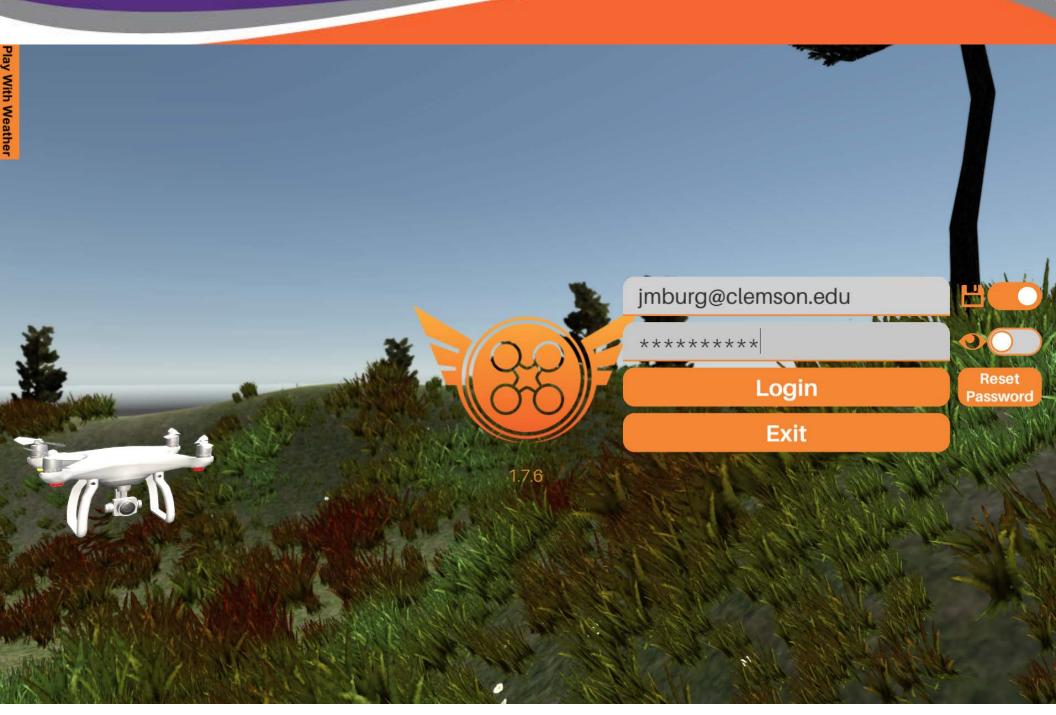
Studio

Analysis Tool

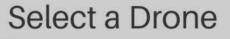












Zephyr Drones



Phantom 3



Phantom 4

Mavic





Inspire 1

Typhoon

CALL STORM



Inspire 2

Titan



3DR Solo



Syma X5C



Q Search



Phantom 4

The fourth generation of the Phantom series from DJI. This quadcopter includes GPS, 3-axis gimbal, and forward optical collision avoidance. Released in 2016, the Phantom 4 features a top speed of 20 m/s and flight time of around 28 min.

Bebop 2



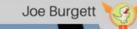
AG-6A HD Racer

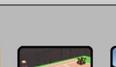


Matrice

Change Module









Tutorial

General

Basic Training

The Hill

Yard



Drones

Industry-Specific Scenarios



Skipl Tower Inspection ition E



Bridge



Obstacle

Course

TRAINING

NIST Training

Course

100



Community Park

TEST

NIST Testing

Course

T

134



Q Search

Parking Lot



Drone Racing



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Tutorial
The tutorial for Zephyr. Start here if you are a
beginner.
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Load Scenario





Monopole



Columns

Tower

Lattice



Circle the

Tower

Tower

Circle the Around the Tower

Tower

columns Around the Circle the Tower (LOS Signal Feed

Loss)





Tower (Random Signal Feed Loss)



(Random Signal Feed Loss)



Columns Around the





Columns Around the Tower

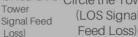


Columns Around the Circle the Tower Circle the Tower (LOS Signal Feed

Tower

(LOS Signal Feed

Loss)



columns Around the Circle the Tower

(LOS Signal

Feed Loss)

(LOS Signal



Tower

(Random Signal

Feed Loss)

Tower (Random Signal Feed Loss)



(Random Signal

Feed Loss)

Circle the Tower (Random Signal Feed Loss)



Circle the Tower

Best Score: N/A

Grade: N/A

Select Module

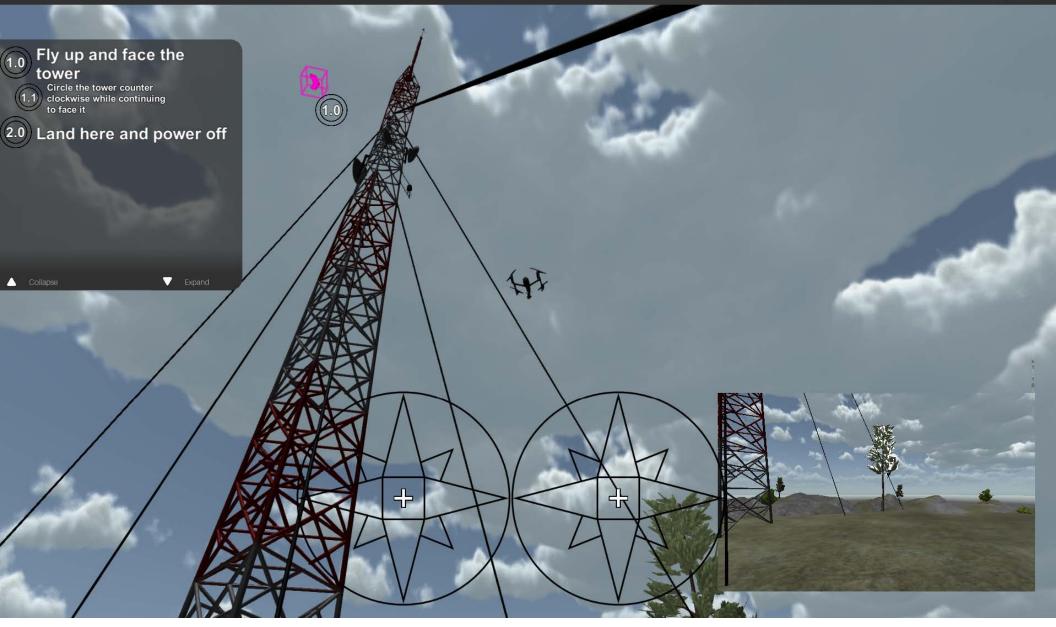




Columns Around the Circle the Tower

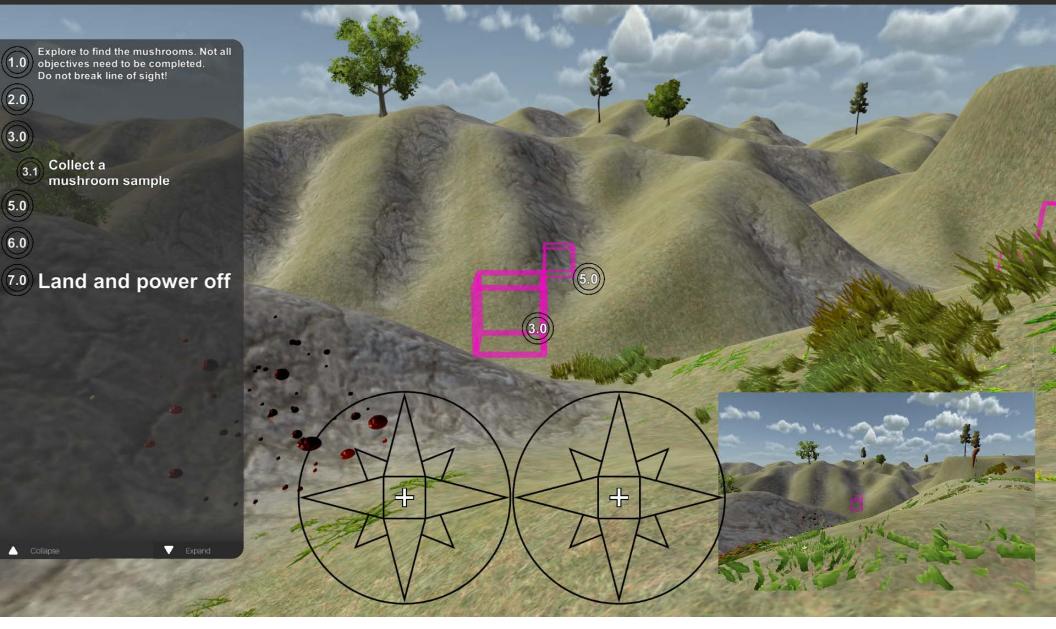


GPS CM IOCOff H West D 0000.85 FT ^ ↓ 00 00 St 0000.06 MPH A 0024.50 FT 1 99% =

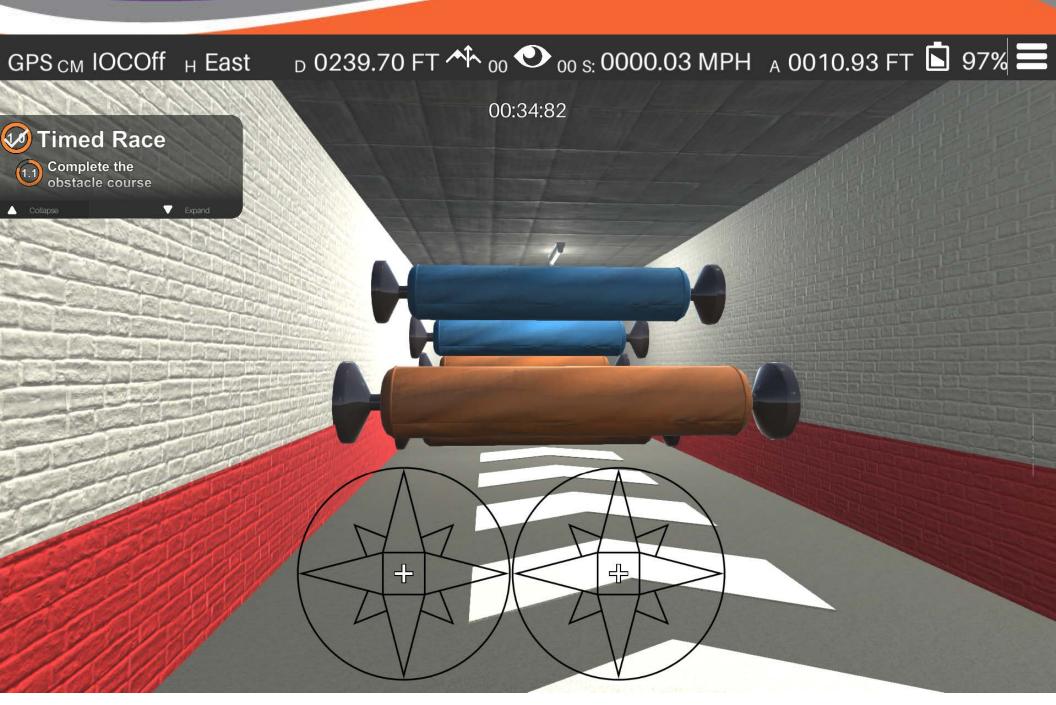




GPS_{CM} IOCOff _н West _D 0088.47 FT 🐴 ₀₀ 👁 _{00 S:} 0000.07 MPH _A 0010.40 FT ь 98% **=**









V Expand

GPS см IOCOff н East D 0188.42 FT 🐴 00 😷 01 S: 0000.08 MPH A 0011.38 FT 🖒 93% 🚍

4.0 3.0

5.06.0

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2.Ô^{.0}

THE.

- 1.0 Playground Challenge
- 2.0 Slide

△ Collapse

P

- 3.0 See-saw 1
- 4.0 See-saw 2
- 5.0 Dome Outside
- 6.0 Monkey Bars

MARATA



GPS см IOCOff н South D 0000.19 FT л 00 00 S: 0000.06 MPH A 0011.55 FT Ь 99% Ξ





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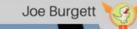
4.0

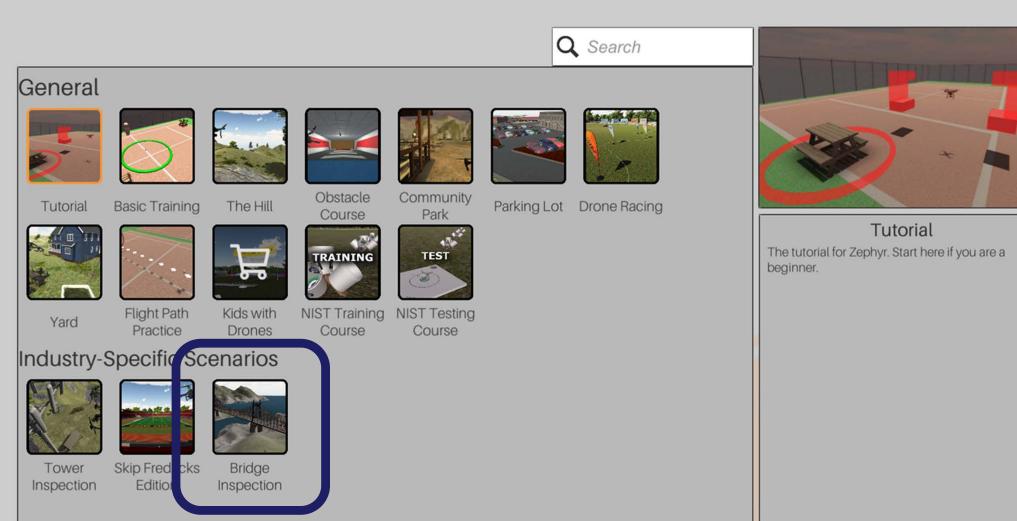
4-

+

Take off and hover in the indicated spot at 6.5ft.
Fly straight out following the arrows closely for 10 meters.
Hold a hover at 6.5ft in the center of the ring.
Fly straight back following the arrows closely for 10 meters.
Fly straight back following the arrows closely for 10 meters.
Hold a hover at 6.5ft in the center of the ring.
Hold a hover at 6.5ft in the center of the ring.
Land the drone as closely as you can to the center of the starting point.

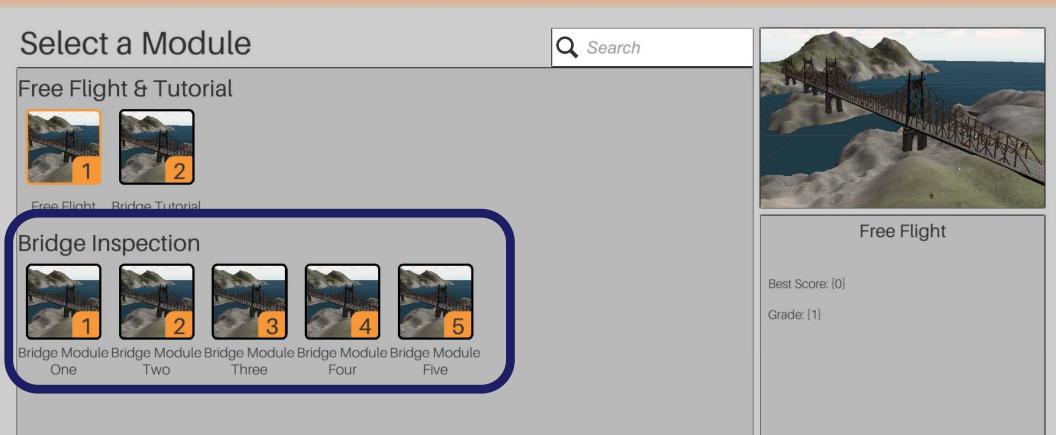






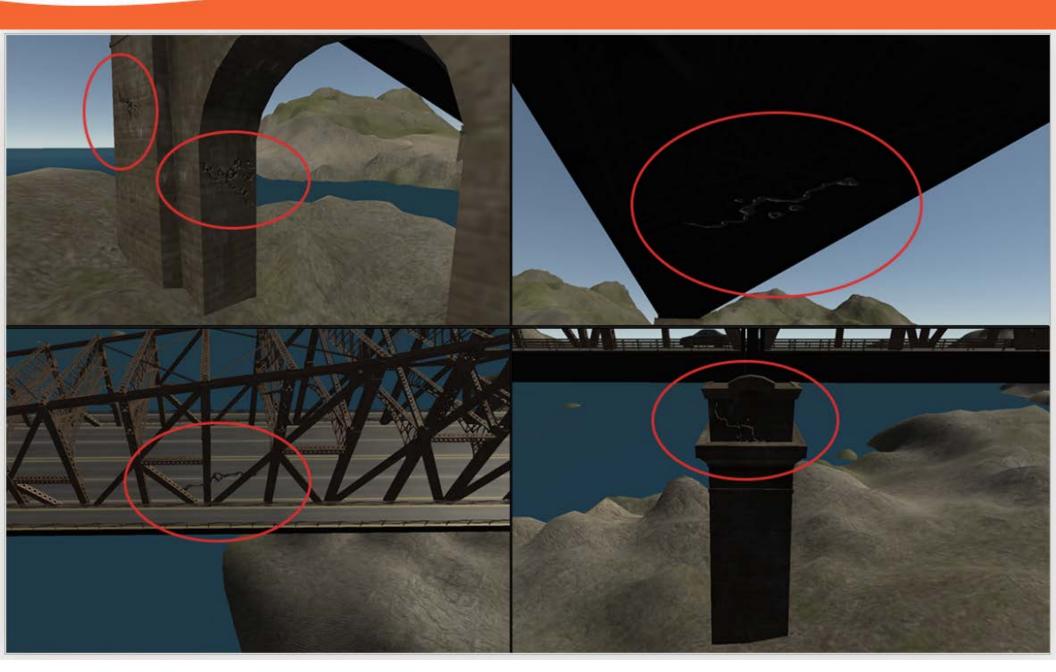


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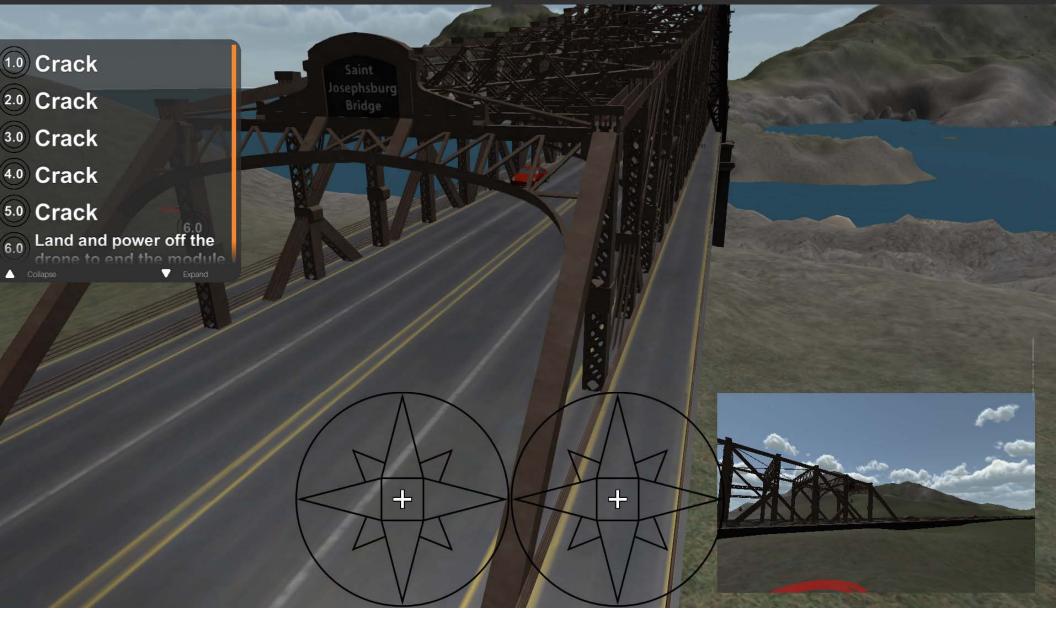
GPS см IOCOff н East D 0254.89 FT 🐴 00 🗢 00 S: 0000.09 MPH A 0022.30 FT 🗅 97% 💳

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- 1.0 Crack 2.0 Crack
- 3.0 Crack
- 4.0 Crack
- 5.0 Crack
- 6.0 Land and power off the drone to end the module







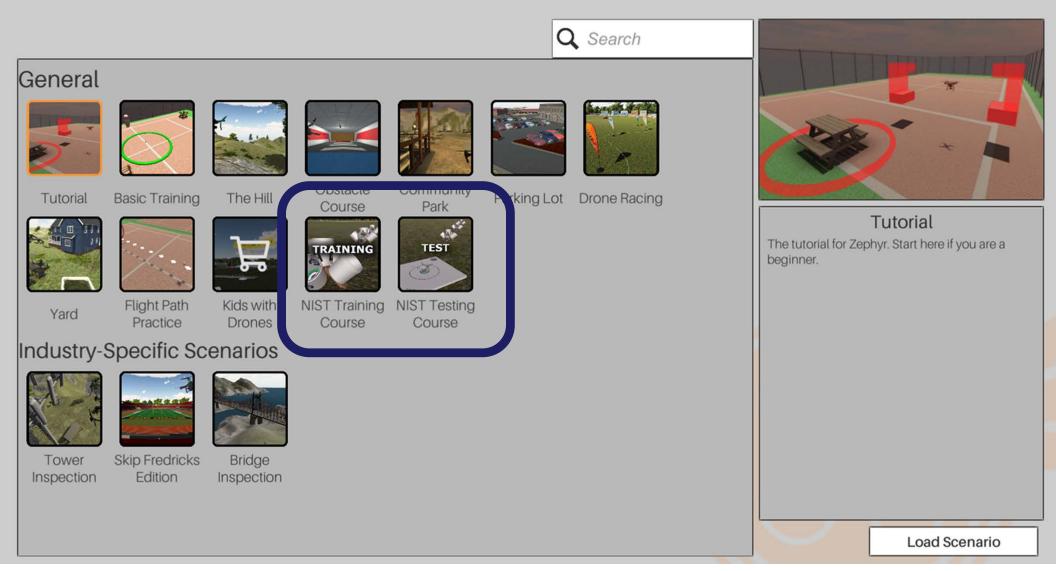
GPS _{CM} IOCOff _H West _D 0671.50 FT [▲] ₀₀ [●] _{00 S:} 0000.03 MPH _A 0075.22 FT **b** 91% **=**

- 1.0 Crack
- 2.0 Crack
- 3.0 Crack
- 4.0 Crack
- 5.0 Crack
- 6.0 Land and power off the

GPS_{CM} IOCOff _H West _D 0671.28 FT [▲] 00 ^O 00 S: 0000.03 MPH _A 0075.21 FT **D** 90% **=**

- 1.0 Crack
 2.0 Crack
 3.0 Crack
 3.0 Crack
 Crack
- 5.0 Crack
- 6.0 Land and power off the drone to end the module
- 🔺 Cái





SI

Joe Burgett









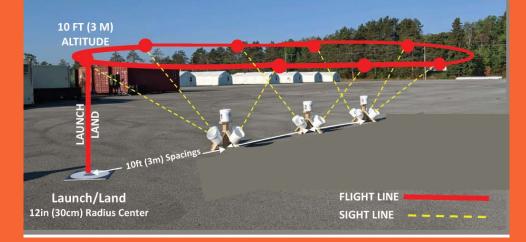


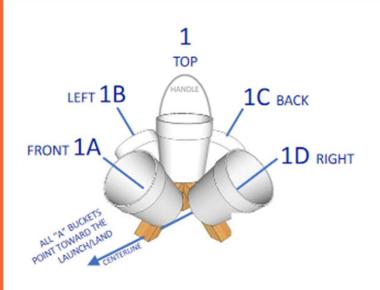
Standard Test Methods for Small Unmanned Aircraft Systems

Basic Proficiency Evaluation for Remote Pilots

TRAVERSE TEST

Right and Left Ovals Around All Three Bucket Stands







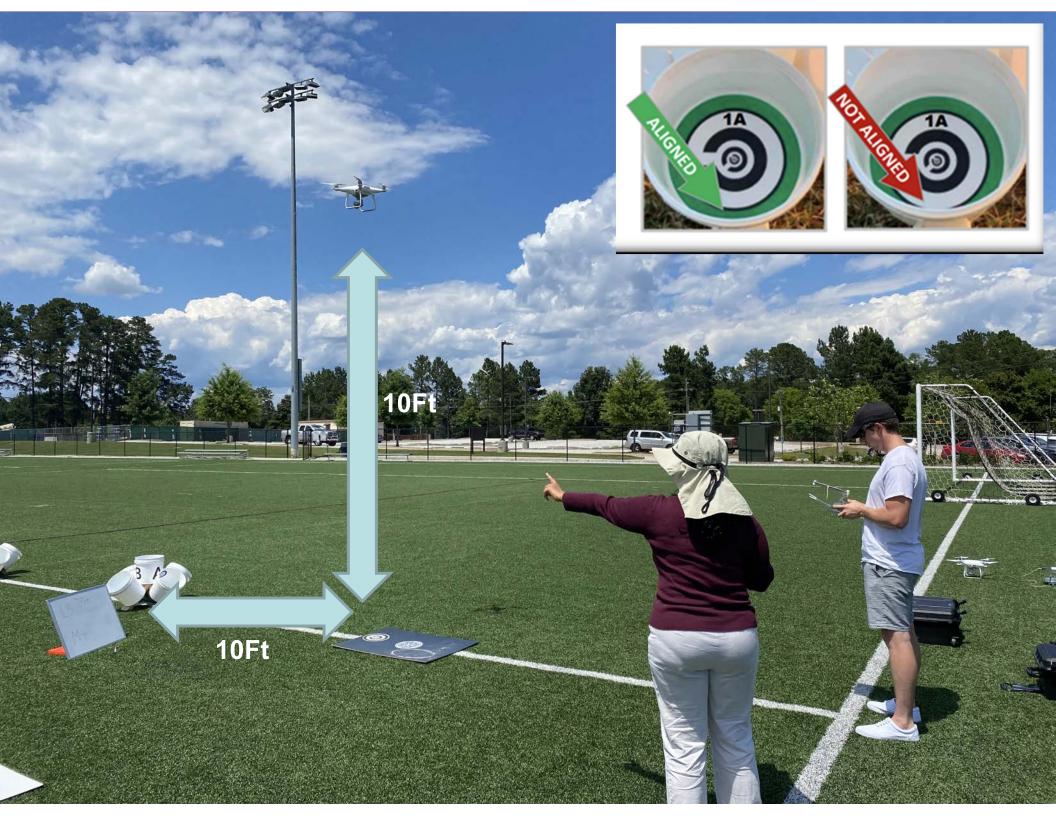
A.T.

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130

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10ft Testing











Test

TEST

Spiral Test

1.24 M



Ten Foot Ten Foot Position Test Traversal Test

Ten Foot Orbital Test

Ten Foot Spiral

Ten Foot

Recon Test

20ft Testing



and a 0 Twenty Foot Twenty Foot

134

134

2

TEST

Twenty Foot Position Test Traversal Test Orbital Test

TEST

130

3

130

3

Twenty Foot



Twenty Foot Recon Test

30ft Testing





Thirty Foot Position Test Traversal Test



Thirty Foot Orbital Test

TEST

Thirty Foot Spiral Test



Thirty Foot **Recon Test**





Ten Foot Position Test Complete the NIST 10ft Positional lane.

Target S Altitude: 10ft(7-13ft) Target Time: < 5:00

Best Score: [0]

Grade: [1]



TEST Call and



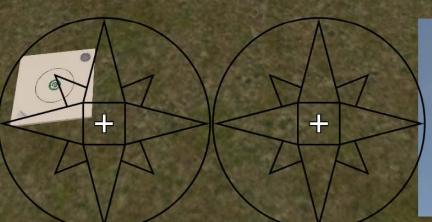
GPS_{CM} IOCOff _н North _D 0018.15 FT 🐴 ₀₀ 👁 _{00 S:} 0000.04 MPH _A 0026.67 FT 🖒 98% 💳

00:30:24

37

32

1. Align and capture 1.0 target 1 2. Align and capture target 1A 2.0 3. Align and capture 3.0 target 1B 4. Align and capture target 1C 4.0 5. Align and capture 5.0 target 1D 6. Align and capture 6.0 target 2 7.0 7. Align and capture target 2A 8. Align and capture 8.0 target 2D 9. Align and capture V Expand



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DISMISS

7:23 PM 3/29/2022



Closing Comments

- Commissioned Study

 Pilot test a FHWA Flight Proficiency Certification
 - Participants / Steering Committee Members
- Access to software
 - 10 licenses to all state DOTs at no cost
 - Email JMBurg@clemson.edu





Questions



Joseph M. Burgett, PhD Associate Professor <u>imburg@Clemson.edu</u> www.clemsondrone.com